



Convex Hull-based Feature Selection in Application to Classification of Wireless Capsule Endoscopic Images

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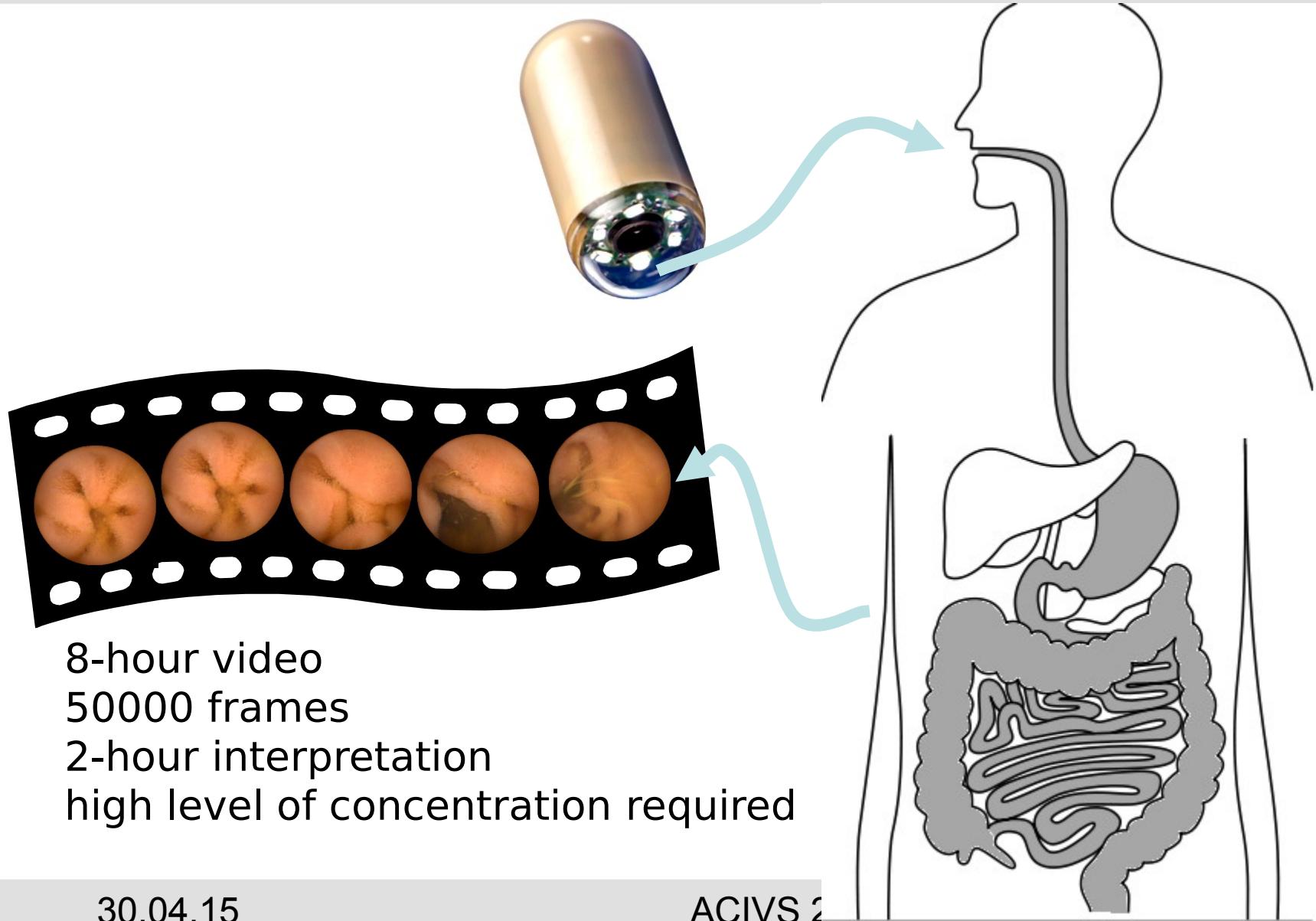


Scope of the presentation

- ✗ Wireless capsule endoscopy
- ✗ Aiding the WCE video interpretation
- ✗ Image descriptors and MaZda software
- ✗ Feature selection problems
- ✗ Vector supported convex hull
- ✗ Experiment
- ✗ Conclusions



Wireless capsule endoscopy





Aiding the video interpretation (Image processing)

Motion analysis:

- scanning the image of intestine surface
(*Szczypinski, et.al*)
- contraction detection and video playback control
(*Vilarino, et.al; Szczypinski, et.al*)

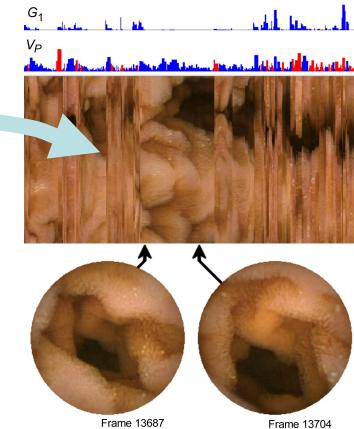
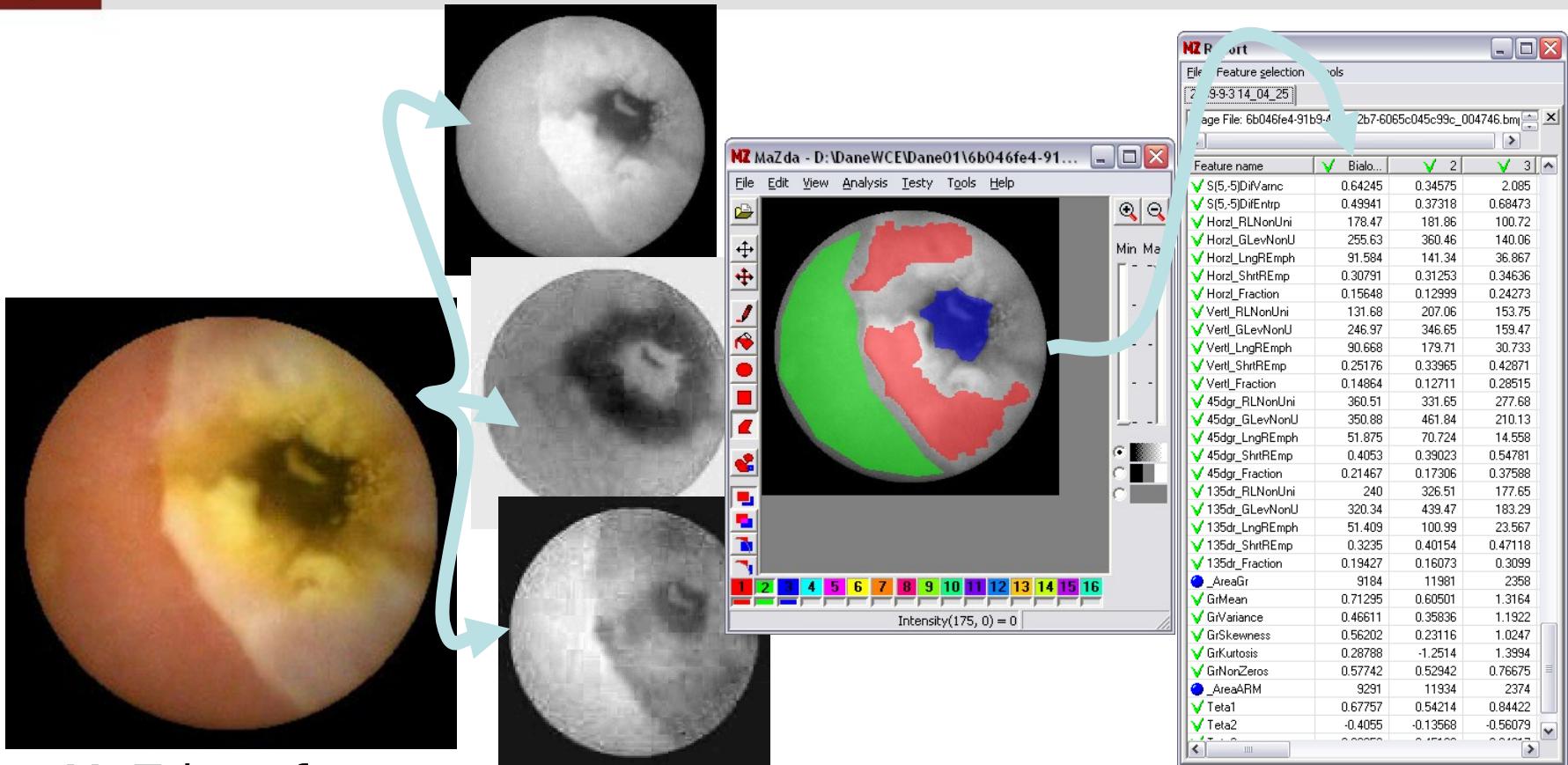


Image color and texture descriptors:

- segmentation of gastro-intestinal tract into sections
(*Coimbra, et.al*)
- image classification and pylorus detection
(*Mackiewicz, et.al*)
- detection of pathology images
(*GivenImaging®; Baopu Li, Max Q.-H. Meng*)



Color and texture descriptors



MaZda software:

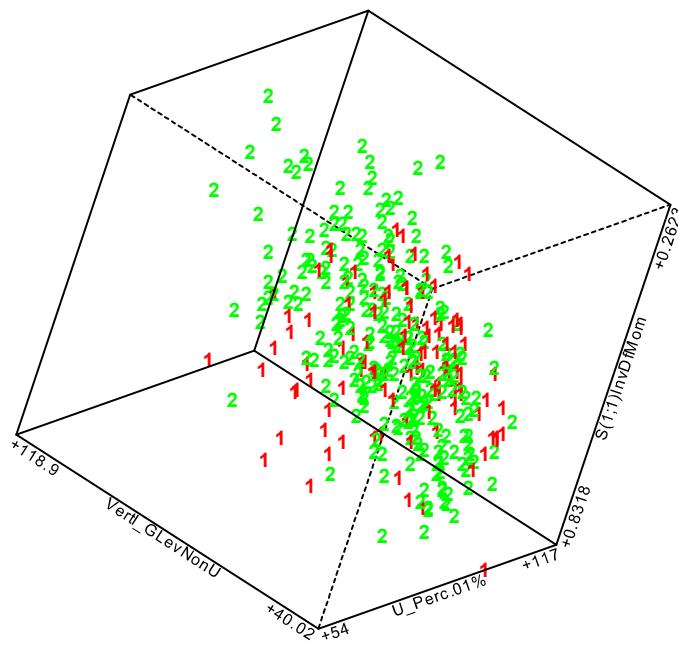
color analysis (**R, G, B, U, V, I, Q, H...**)

regions of interest

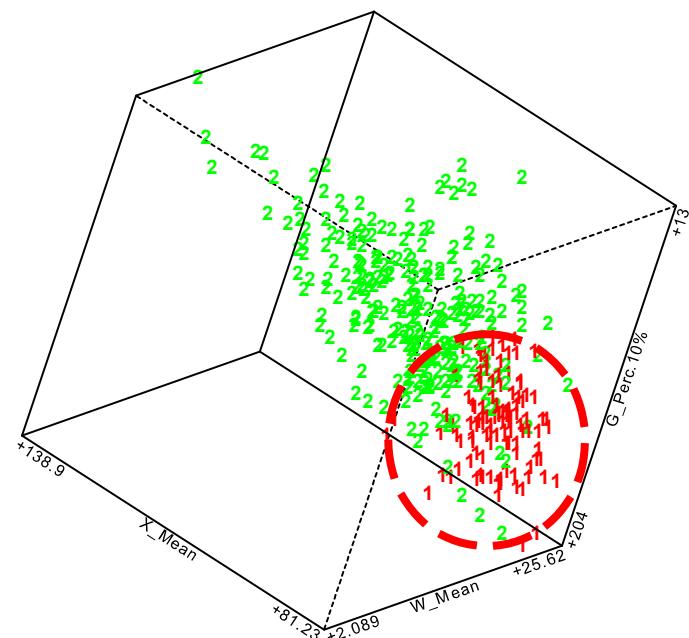
texture descriptors (**histogram, co-occurrence, run-length, gradient, wavelet...**)

Color and texture descriptors (selection)

subspace with poor discrimination ability



subspace with stronger discrimination ability





• Goal and motivation

- Need for development of image processing method for aiding the WCE video interpretation,
- Methods developed for detection of pathology images are still unreliable (high FPR and FNR) and further research is required,

• Problems

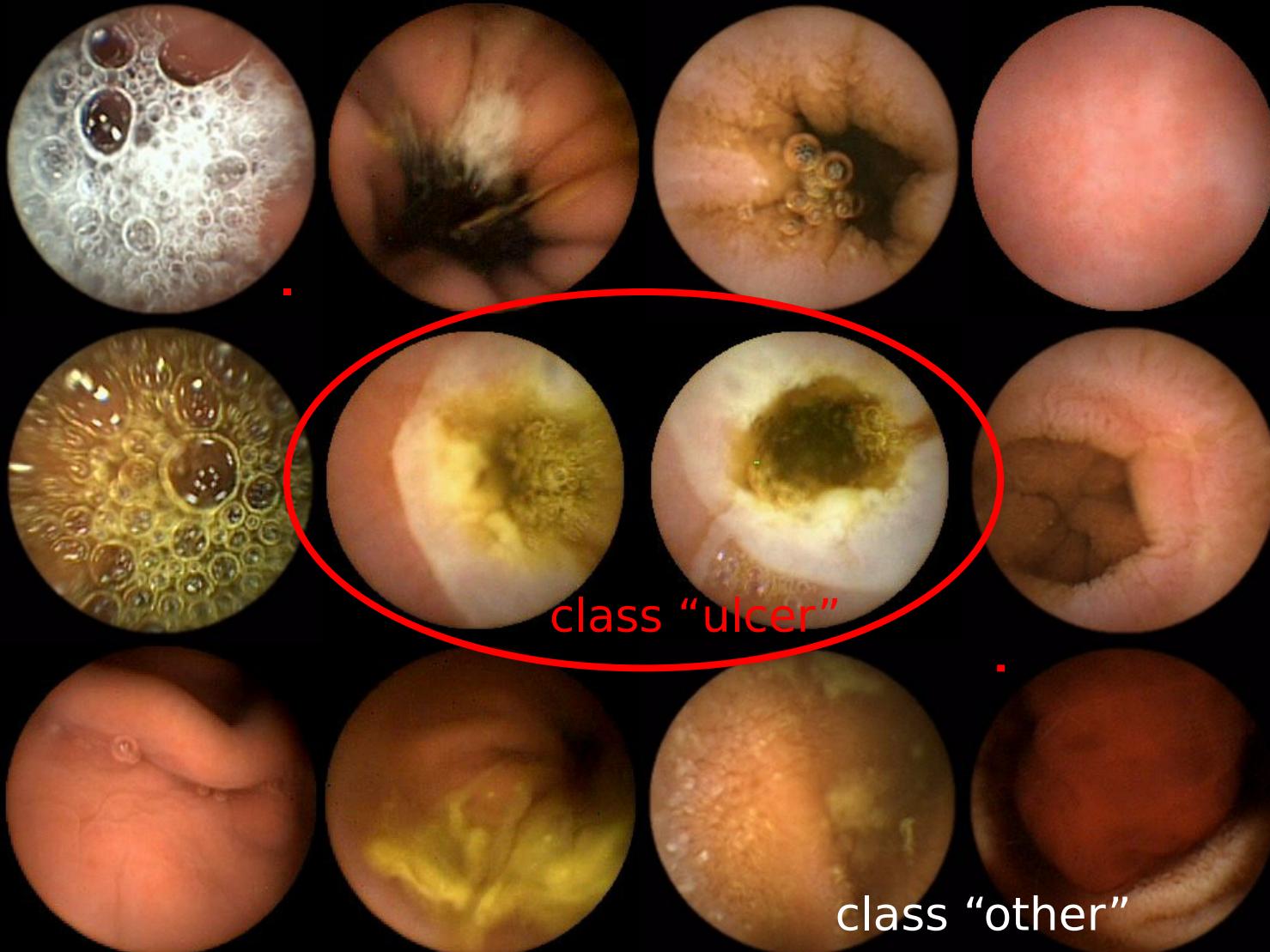
- Selection of images for machine learning and labeling of pathological regions,
- Selection of features with high discriminative power,
- Development of method for endoscopic image classification.

• Means and tools

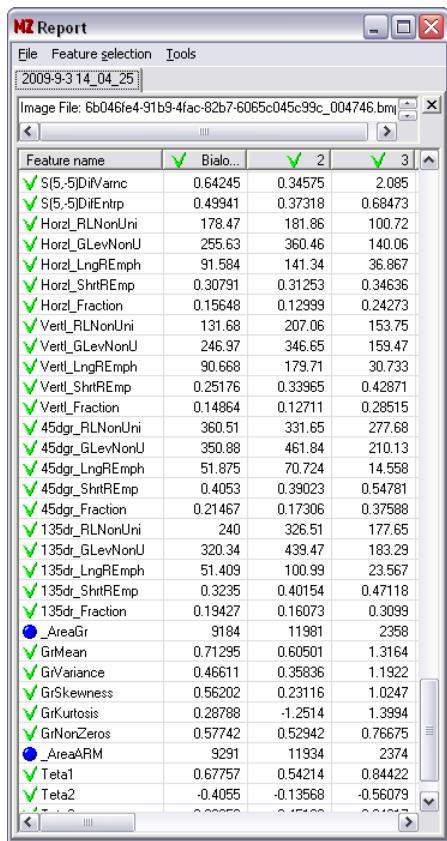
- Collected over 60 WCE videos from AIG India and Uniwersytet Medyczny in Łódź
- Comprehensive tool (MaZda) for computation of color and texture descriptors verified in other medical image analysis applications
- Tools for machine learning (feature selection and reduction, supervised learning and classification)



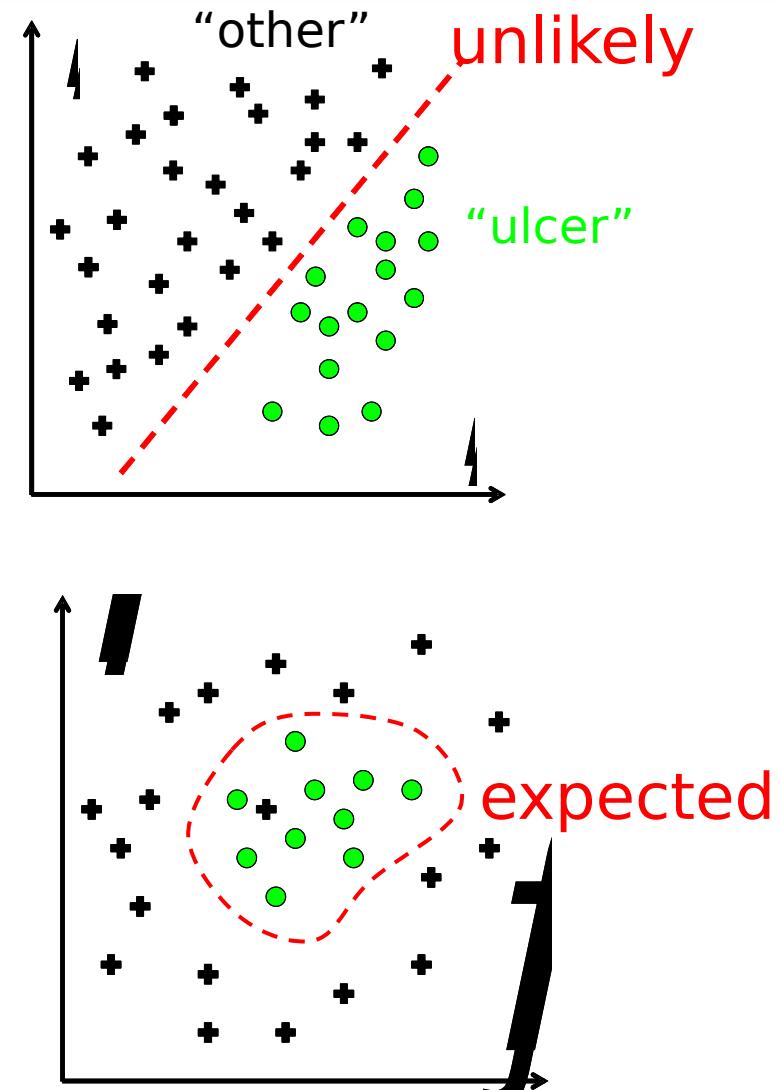
Selection of images



342 features per region (342-dimensional space)

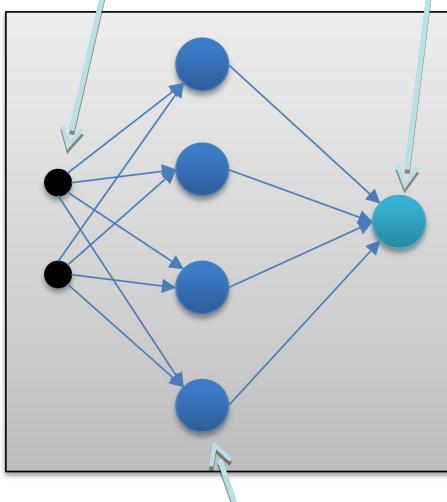


feature selection



Radial Basis Function Networks

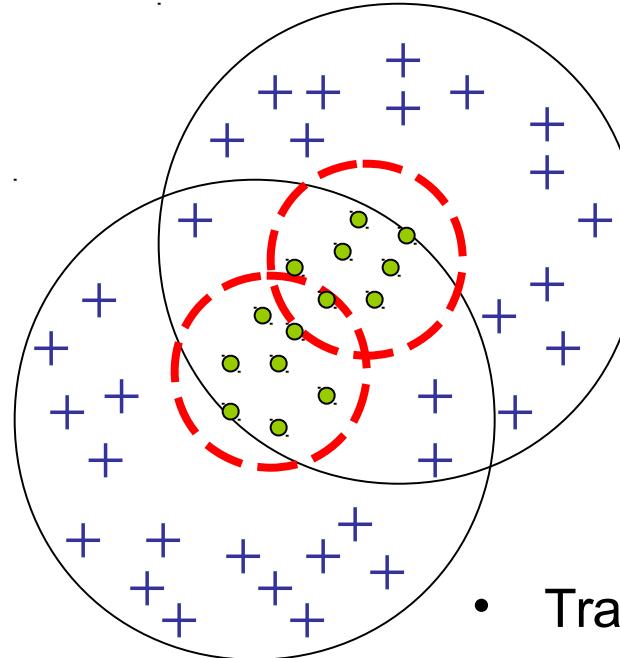
Input nodes
(data vectors) Output unit



Hidden units
(prototype vectors)

Hidden units perform nonlinear distance calculation according to Gaussian kernels:

$$g_i(x) = \frac{1}{(2\pi)^{N/2}\sigma_i^N} \exp\left(-\frac{\|\mathbf{x} - \mathbf{c}_i\|^2}{2\sigma_i^2}\right)$$

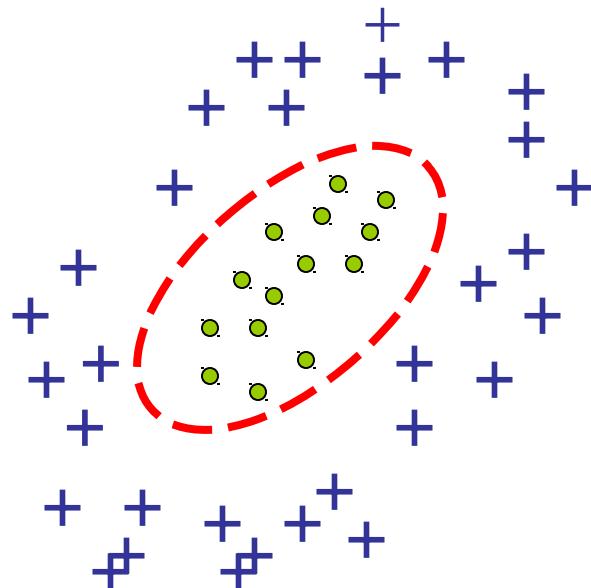


- Training RBFs:
 - K-means clustering
 - \mathbf{c}_i, σ, N
- Training linear weights:
 - Linear or logistic regression



Support Vector Machines

Non-linearly separable classes



Linear decision boundary

$$y(\mathbf{x}) = b + \sum_{\alpha_i \neq 0} \alpha_i y_i \mathbf{x}_i \cdot \mathbf{x}$$

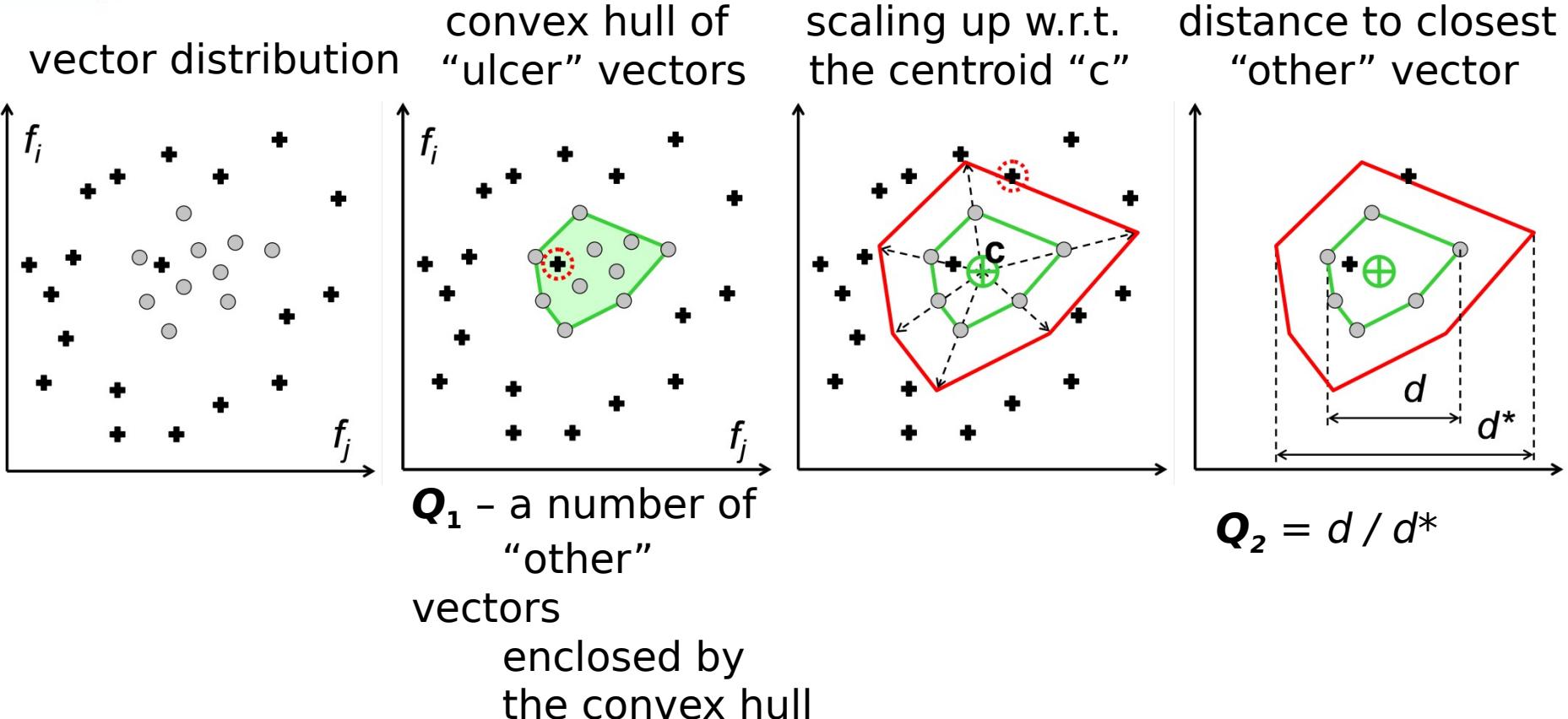
The kernel trick

$$k(\mathbf{x}_i, \mathbf{x}_j) = \exp(-\gamma \|\mathbf{x}_i - \mathbf{x}_j\|^2)$$

How to choose the value of γ ?

Finding α_i and b parameters requires solving a *constrained quadratic optimization* problem. This can be efficiently done through **sequential minimal optimization** (SMO) algorithm.

Vector Supported Convex Hull (concept)



VSCH Penalty factor

$$Q = Q_1 + Q_2$$



Vector Supported Convex Hull (algorithm)

Feature space reduction algorithm:

- Search of 1D, 2D and 3D feature subsets
- Computes the Q factor for each the subset
- Select features from subsets having the lowest Q

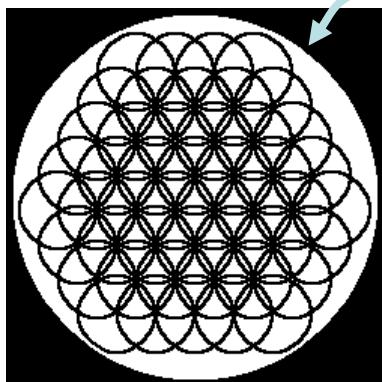
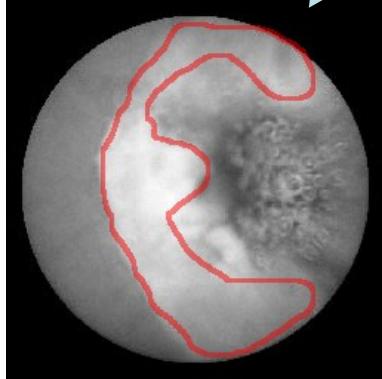
Classification rule:

- Scale the convex hull up with respect to the centroid by the factor of $(Q_2)^{-2}$
- Vectors enclosed by the resulting convex hull are of “ulcer” class
- Vectors outside the convex hull are of “other” class

Method properties:

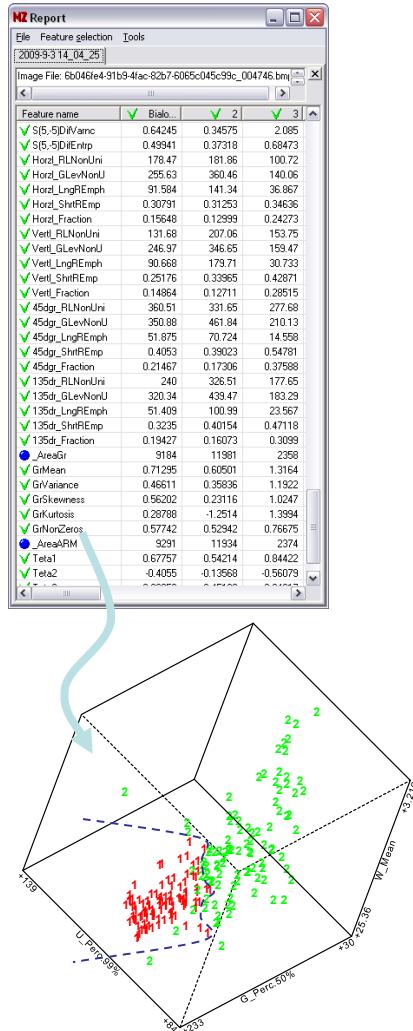
- Fast full search in case quick hull algorithm implemented
- Utilizes natural ability of convex hulls to separate vector clusters surrounded by other vectors

Experiment (feature computation)



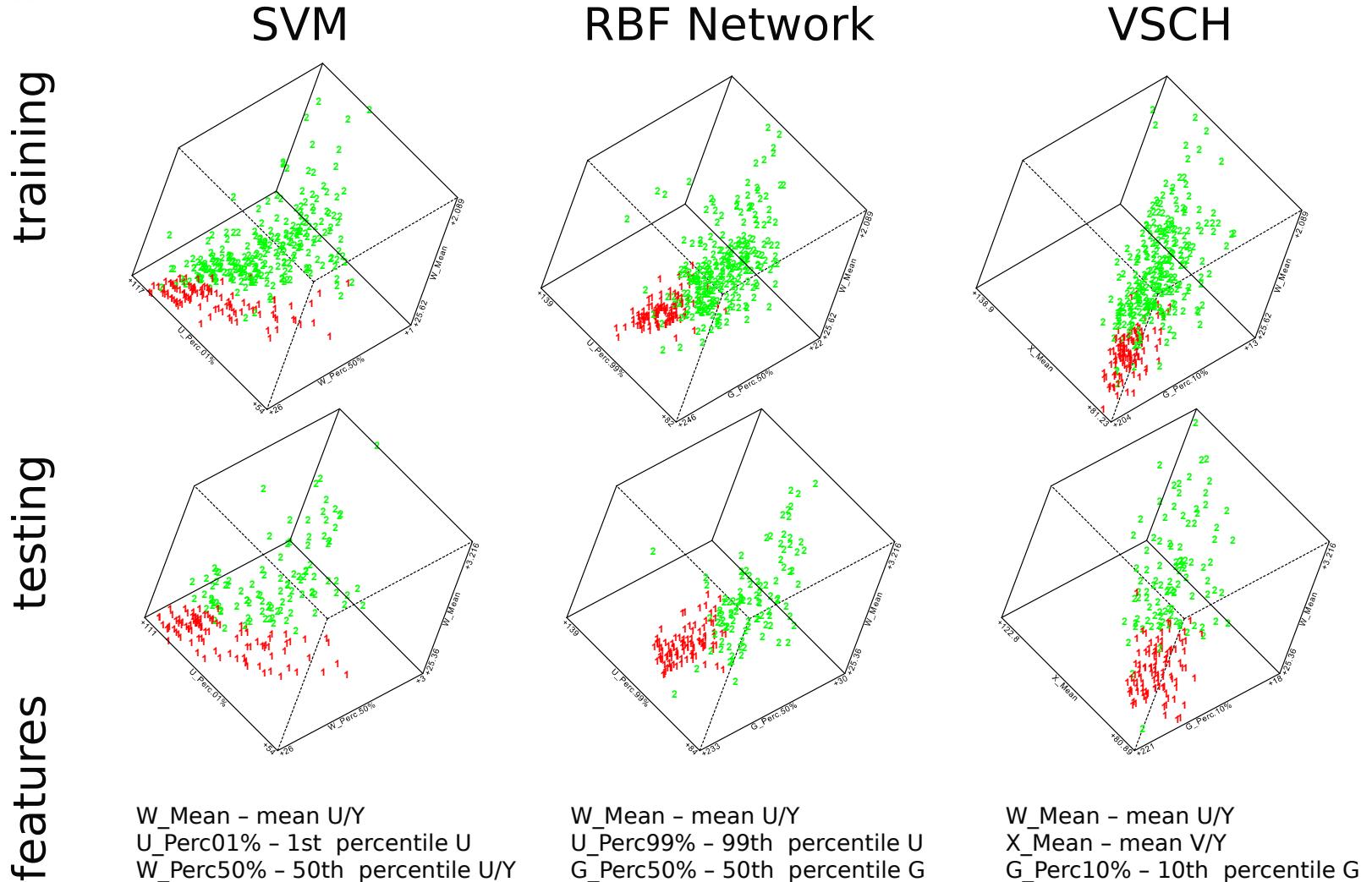
- Selected 50 images with areas of ulceration
- Areas of ulceration manually depicted
- Randomly selected 200 images without ulceration
- Texture and color descriptors computed within 48 circular regions per image
- Feature vectors computed on images without ulceration labeled as “other”
- Feature vectors computed on ulceration images for regions covering ulceration areas labeled as “ulcer”

Experiment (selection)



- Randomly selected training set of 109 vectors of class “ulcer” and 258 vectors of class “other”
- Randomly selected testing set of 100 vectors of class “ulcer” and 100 vectors of class “other”
- VSCH, SVM and RBF networks used for feature selection (3 features out of 342) and finding classification rules (the training set used)
- Results (vectors of selected features and classification rules) verified on the testing set of vectors

Experiment (selection results)





Experiment (classification results)

		FPR [%]	Specificity	FNR [%]	Sensitivity
VSCH	Training	9.3	0.91	0.0	1.00
	Testing	7.0	0.93	6.0	0.94
SVM	Training	4.3	0.96	6.4	0.94
	Testing	5.0	0.95	9.0	0.91
RBF	Training	3.9	0.96	10.1	0.90
	Testing	9.0	0.91	9.0	0.91

Computation times (selection of feature pairs)

Intel Core 2 Quad @2.83 GHz (single thread in both cases)

- **VSCH, C++ implementation of quick hull algorithm - 10 minutes**
- **RBF networks, Java implementation - 2 hours**
- **SVM, Java implementation - 3 hours**



Conclusions

- ✗ We found image descriptors and classification rules for detection of WCE images showing a chosen category of ulceration
- ✗ VSCH compared to RBF networks and SVM has low False Negative Ratio which might be useful in medical diagnosis
- ✗ VSCH is fast and does not require setting of any parameters or standardization of feature space



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